

Départ
(1 appui court)

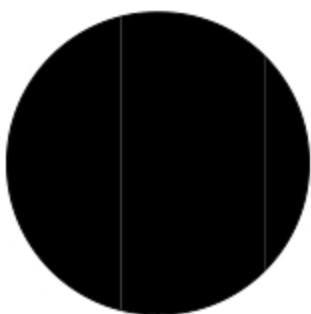
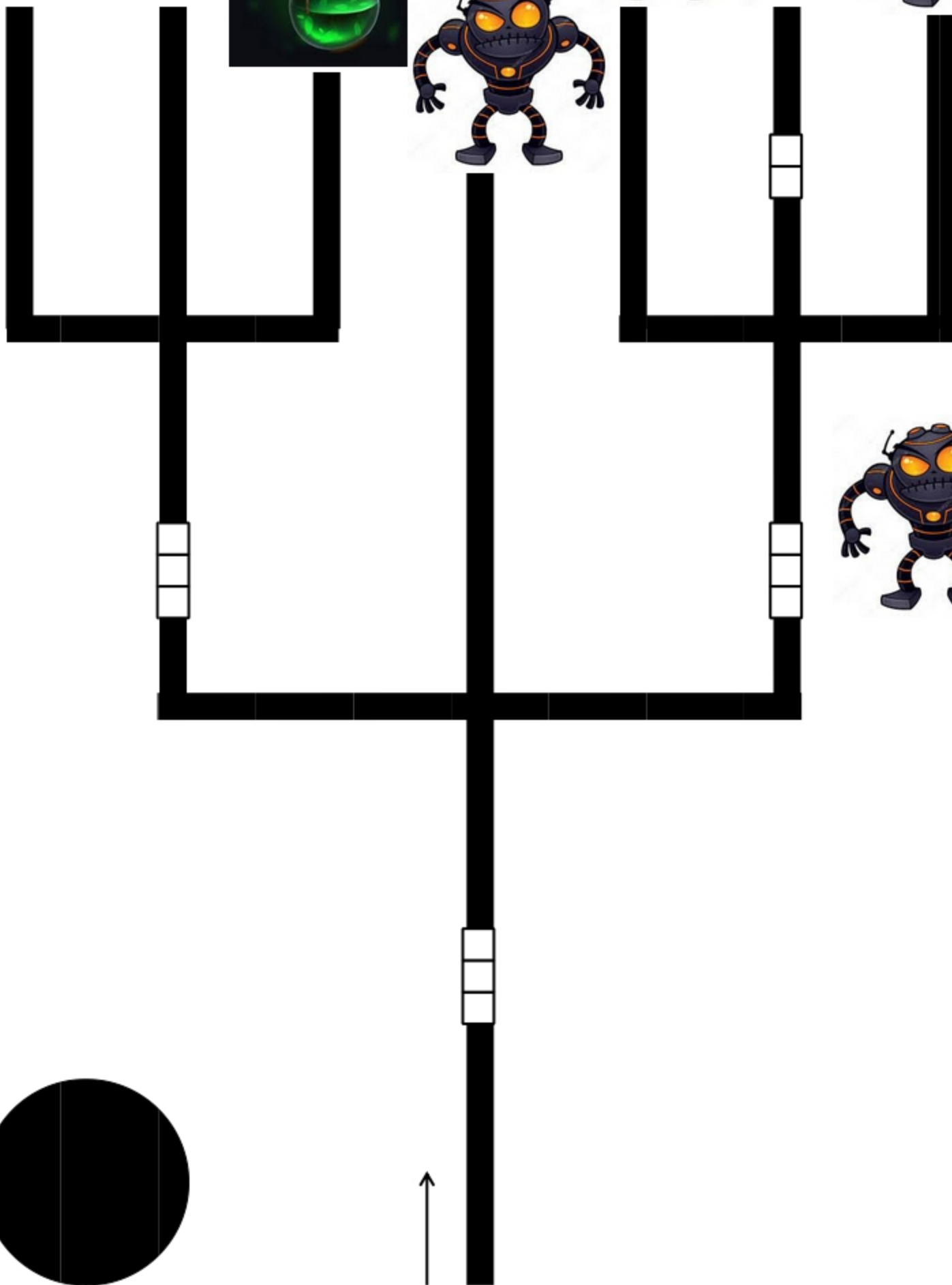


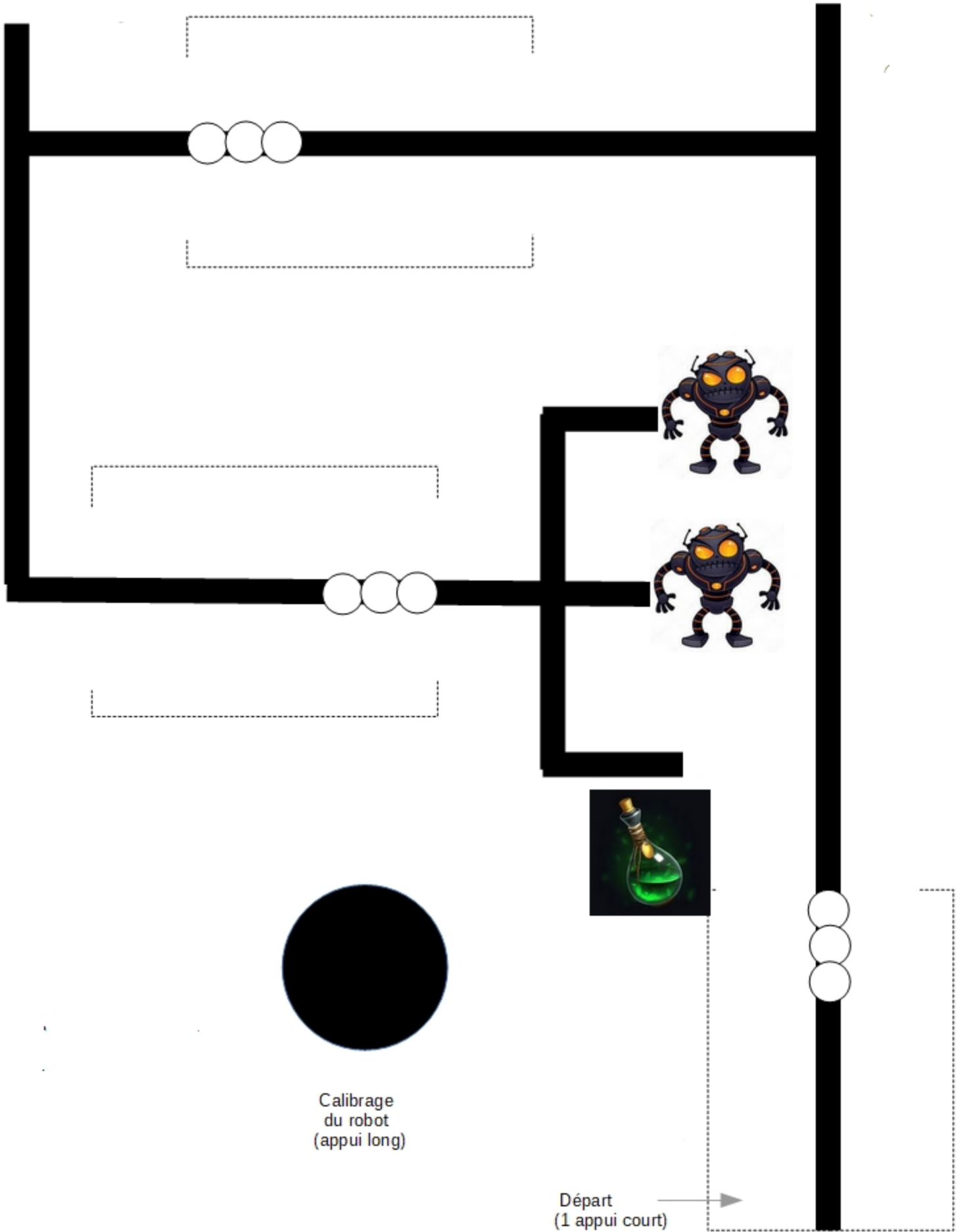


Calibrage
du robot
(appui long)

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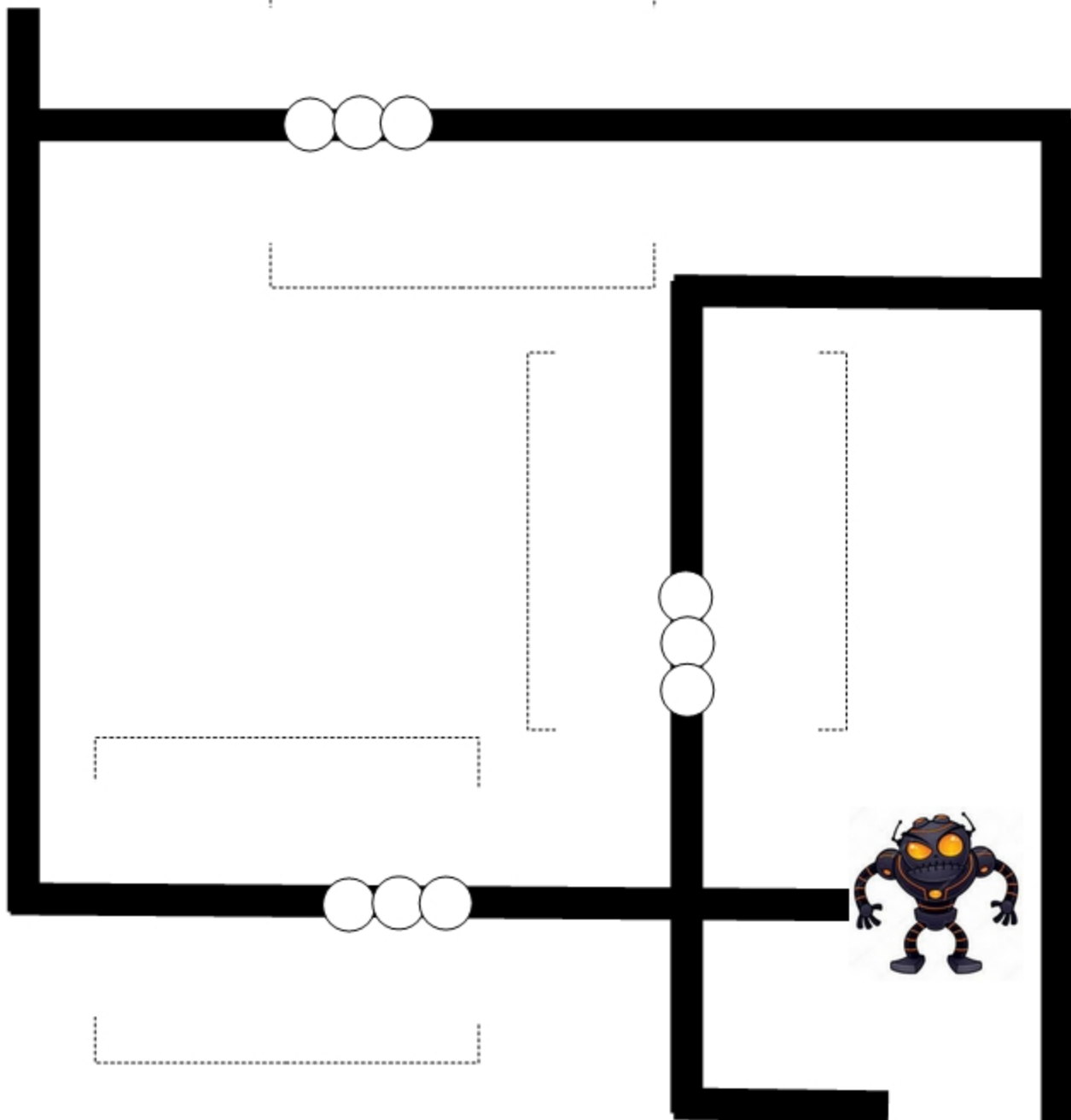






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